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## Linearization of discrete-time control system by state transformation

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Equation (57) of the above article should be read:

$$L_{\Xi_k} \langle \omega_i, \Xi_j \rangle = \sum_{l,q=1}^n \left( \frac{\partial \alpha_{il}}{\partial x_q} \xi_{lj} \xi_{qk} + \alpha_{il} \frac{\partial \xi_{lj}}{\partial x_q} \xi_{qk} + \alpha_{il} \frac{\partial \xi_{lk}}{\partial x_q} \xi_{qj} - \alpha_{il} \frac{\partial \xi_{lk}}{\partial x_q} \xi_{qj} \right).$$

The Estonian Academy Publishers apologizes to the authors and our readers for this error.